### Datasheet

# Variable frequency drive VYBO Electric a.s.



## Type: V810-4T1100

#### V810 series 400V



Rated power	110 kW
Rated output current	210 A
Supply voltage	3 x 400 V
Output voltage	0 – 400 V
Output frequency	0 – 3200 Hz
Overload capacity in ND mode - Normal load (N. Duty)	120% / 60 s
Overloading in HD mode - Heavy load (H. Duty)	150% / 60 s
Control mode V/F scalar control	<b>~</b>
Open-loop vector SFVC control mode	<b>✓</b>
Closed-loop vector CLVC control mode	<b>✓</b>
Analog inputs	2
Digital inputs	8
Analog outputs	2
Relay outputs	2
Open collector outputs	1
Brake transistor	×
EMC filter	<b>✓</b>
+10 V output	✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓
+24 V output	<b>✓</b>
Input for PTC	<b>✓</b>
Safe Torque Off (STO)	×
Emergency STOP (EMS)	<b>~</b>
Integrated Ethernet	×
Integrated MODBUS RTU	<b>✓</b>
PROFIBUS	<b>✓</b>
PG card for encoder	<b>~</b>
PID	~
PLC intelligent function	<b>✓</b>
External panel connection (normally up to 30 m)	<b>*</b>
Degree of protection IP 20	<b>✓</b>
Degree of protection IP 65	×
Change of direction of rotation via external input	<b>✓</b>
Change of direction of rotation from the panel	<b>✓</b>

#### Detailed specification

VFD model type V810	Rated output power (kW)	Maximum input current (A)	Rated output current (A)	Recommended motor power (kW)
V 810-4T1100	110	210	210	110

Input voltage (V) 50/60Hz	Power (kW)	Cross section of the voltage cable (mm²)	Recommended circuit breaker (A)
3 PH 3 x 400 V	110	95	250

#### Table of suitable braking resistors

Braking resistance					
Type of VFD	Resistor power (W)	Resistance value (Ω) (≥)	Braking unit CDBR	Braking moment (10% ED)	Recommended power (kW)
V 810-4T1100	4500*2	9.4*2	External	125	110

#### General technical parameters for all types of V810

	Input voltage range:	1 x 230 V AC ± 15%
		3 x 400 V AC ± 15%
Power supply		3 x 690 V AC ± 15%
	Power frequency range:	47 to 63 Hz
Control mode	V/F scalar control	
	SFVC vector with open circuit	
	CLVC vector control	
Maximum frequency	SFVC, CLVC vector cont	rol: 0 - 320 Hz
	V/F scalar control: 0 - 32	200 Hz
	1 - 16 kHz	
Carrier frequency	The carrier frequency is automatically set	
	based on the load chara	cteristic.
Input frequency resolution	Digital setting 0.01 Hz	
	Analog setting: maximur	n frequency x 0.025%

	0.1 (4.5.0.0) (0.5)(0.5)	
Initial torque	G type: 0.5 Hz / 150 % (SFVC)	
	P type: 0.5 Hz / 180 % (CLVC)	
	P type: 0.5 Hz / 100 %	
Speed range	1:100 (SFVC)	
	1:1000 (CLVC)	
Speed stability	± 0.5% (SFVC)	
Speeu stability	± 0.02% (CLVC)	
Torque control accuracy	± 5% (CLVC)	
	G type: 60s for 150% of rated current, 3s for 180% of	
Overloadability	rated current.	
Overloadability	P type: 60s for 120% of rated current, 3s for 150% of	
	rated current.	
Increase torque	Auto-boost or user manual increment 0.1% to 30.0%	
	Linear V/F curve	
V//E our /o	Multipoint V/F curve	
V/F curve	N-voltage V / F curve (multiple of 1.2-voltage, 1.4-voltage,	
	1.6-voltage, 1.8-voltage, adjusted)	
V/F separation	Two types: full separation; half separation	
	Linear ramp	
Ramp modes	S-curve ramp	
	4 groups of acceleration / deceleration times with a range of 0.0-6500.0 s	
	8 digital inputs, binary ON / OFF inputs, 1 terminal X5 can	
	support high speed pulse input. All terminals have	
Input terminals	have optional PNP or NPN	
	2 analog inputs, one of which FIV supports -10 V / +10 V; or a O-10 V input	
	and the second FIC supports a 0-10V or 0-20mA (4-20 mA) input.	
	1 Programmable open collector output:	
Output terminals	provides 1 output terminal (open collector	
	output or high speed pulse output)	
	2 relay outputs,	
	2 analog outputs: FOV and FOC with optional	
	0 – 20 mA (4 – 20 mA) or 0 – 10 V output	
	The drive is equipped with a port for PG cards (for encoder),	
PG cards	or PG cards for use with a resolver, etc.	
	Jan . S sai do foi dos mara rosorvoi, oto.	

	Braking frequency: 0.0 Hz to maximum frequency		
DC braking	Braking time: 0.0-36.0 s		
	Braking current value: 0.0% -100.0%		
Brake unit	Models up to 18.5 kW have a built-in brake unit as standard.		
Control in JOG mode	JOG frequency range: 0.00-50.00 Hz		
(stepping)	JOG acceleration / deceleration time: 0.0-6500.0 s		
Implem. more preset speeds	Implemented up to 16 speeds using a simple PLC function		
implem. More preset speeds	or a combination of X end states.		
PTC	Input for PTC motor or thermal contact protection.		
Built-in PID regulator	Facilitates a process-controlled closed-loop control system.		
Automatic AVR	It can automatically maintain a constant output voltage		
voltage regulation	when the supply voltage changes.		
Overvoltage and overcurrent control	Current and voltage are automatically limited during operation to prevent frequent tripping due to overvoltage and overcurrent.		
Torque and steering	It can automatically limit torque and prevent		
limitation	frequent overcurrent changes during operation.		
EMS STOP	Emergency stop system: in an emergency, the drive stops immediately		
security feature	after activating EMS STOP.		
Fast current limit	Helps prevent common errors due to AC motor overcurrent		
Lligh porformance	AC motor control is performed by high-performance		
High performance	vector current control technology.		
Time Management	Time range: 0.0-6500.0 minutes		
Communication	MODBUS RTU, PROFIBUS-DP (from 5,5 kW)		
Boot Command Channel	Depending on the panel, control terminals, the serial communication		
boot Command Chainei	port can be switched in many ways		
	10 types of frequencies, given by digital analog voltage		
Frequency source	analog current, pulse, serial port, X8, PID, can be		
	switched in many ways		
Auvillany frantiana y agurag	10 kinds of frequencies, micro adjustment can be		
Auxiliary frequency source	easily implemented, frequency synthesizer		
LED display	Displays parameters		
Lock keys and select features	Can block buttons partially or completely and define the range of functions of some buttons to prevent malfunctions.		
Protection mode	Motor short-circuit detection, output phase loss protection, overcurrent protection, overvoltage protection, live protection, overheat protection and overload protection.		

EMC (compatibility)	IE 61000-4-6; IEC 61000-4-4; IEC 61000-4-11; IEC 61000-4-5
Standards	EN/IEC 61800-3:2017; C1, which is suitable for the 1st environment;
Stariuarus	EN/IEC 61800-3:2017; C2, which is suitable for the 1st environment;
Installing in an environment	Install indoors, avoid direct sunlight, salt, dust,
	corrosive or flammable gas, smoke, steam.
	Resistance to chemical contaminants class 3C3 EN/IEC 60721-3-3
	Dust pollution resistance 3S3EN/IEC 60721-3-3.
Height above sea level	Under 1000 meters above sea level. (reduce the power level when used above 1000 meters above sea level.)
Ambient temperature	– 10 ° C to 40 ° C (reduce power level if ambient temperature is between 40 ° C to 50 ° C)
Humidity	Less than 95% relative humidity, no condensation IEC 60068-2-3
Vibration	Less than 5.9 m / s2 (0.6 g) IEC 60068-2-6
Storage temperature	- 20 °C to + 60°C

