Datasheet

Variable frequency drive VYBO Electric a.s.



V800 series 400V



| Type: V800-4T0011 | Electric |
|--|---------------------------------------|
| Rated power at normal load (Normal duty) | 1,1 kW |
| Rated power for heavy load, heavy starts (Heavy duty) | |
| Rated output current | 3 A |
| Supply voltage | 3 x 400 V |
| Output voltage | 0 – 400 V |
| Output frequency | 0 – 3200 Hz |
| Overloading in ND mode - Normal load (N. Duty) | 120% / 60 s |
| Overloading in HD mode - Heavy load (H. Duty) | 150% / 60 s |
| Control mode V/F scalar control | |
| Open-loop vector SFVC control mode | |
| Closed-loop vector CLVC control mode | × |
| Analog inputs | 2 |
| Digital inputs | 6 |
| Analog outputs | 1 |
| Relay outputs | 1 |
| Open collector outputs | 1 |
| Brake transistor | |
| EMC filter | |
| +10 V output | |
| +24 V output | × |
| Input for PTC | |
| Safe Torque Off (STO) | × |
| Emergency STOP (EMS) | |
| Integrated Ethernet | × |
| Integrated MODBUS RTU | ~ |
| PROFIBUS | × |
| PG card for encoder | × × × |
| PID + dry run detection LL + sleep mode SLP + high/low pressure detection HP/LP | ✓ |
| PLC inteligent function | ✓ |
| External panel connection (normally up to 50 m) | ✓ |
| Degree of protection IP 20 | ✓ |
| Degree of protection IP 65 | × |
| Change of direction of rotation via external input | · · · · · · · · · · · · · · · · · · · |
| Change of direction of rotation from the panel | × |

Detailed specification

| Type of VFD V800 | Rated output power (kW) | Maximum input current (A) | Rated output current (A) | Recommended motor power (kW) |
|------------------|----------------------------------|---------------------------|-----------------------------|------------------------------------|
| V 800-4T0011 | 1,1 | 4,5 | 3 | 1,1 |

| Input voltage (V) | Power | Cross section of the voltage | Recommended circuit breaker (A) |
|-------------------|-------|------------------------------|---------------------------------|
| 50/60Hz | (kW) | cable (mm²) | |
| 3 PH 3 x 400 V | 1,1 | 1,5 | 10 |

Table of suitable braking resistors

| | | Braking resistance | | |
|--------------|---------------------------|----------------------------------|--------------|---------------------------|
| Type of VFD | Resistor power (kW) | Resistance value (Ω) (≥) | Braking unit | Recommended power (kW) |
| V 800-4T0011 | 0,15 | 220 | Integrated | 1,1 |

General technical parameters for all types of V800

| Control mode | V/F scalar control |
|----------------------------|--|
| | SFVC vector control with open circuit |
| Maximum frequency | SFVC vector control: 0 - 320 Hz |
| | V/F scalar control: 0 - 3200 Hz |
| Carrier frequency | 1 - 16 kHz |
| | The carrier frequency is automatically set |
| | based on the load characteristic. |
| Input frequency resolution | Digital setting 0.01 Hz |
| input frequency resolution | Analog setting: maximum frequency x 0.025% |
| Initial torque | G type: 0.5 Hz/150% (SFVC) |
| | P type: 0.5 Hz/100% |
| Speed range | 1:100 (SFVC) |
| Speed stability | ± 0.5% (SFVC) |
| Torque control accuracy | ± 5% (SFVC) |

| | G type: 60s for 150% rated current, 3s for 180% |
|--------------------------------|---|
| Overload size | rated current |
| | P type: 60s for 120% rated current, 3s for 150% |
| | rated current |
| Torque increase | Fixed torque increase |
| | User increase 0.1%-30.0% |
| EMC filter | Integrated with label "C1" of C1 class. |
| EIVIC TIILEI | Without C2 class label. |
| | Lines V/F curve |
| | Multipoint V/F curve |
| V/F curve | N-voltage V/F curve (multiple of 1.2 voltage, 1.4-voltage, |
| | 1.6- voltage, 1.8 voltage, adjusted) |
| V/F separation | Two types: full separation, half separation |
| | Linear curve |
| Ramp modes | S-curve type ramp |
| | Four groups of acceleration/deceleration times with a range of 0.0-6500.0 |
| | Braking frequency: 0.3 Hz to maximum frequency |
| DC braking | Braking time: 0.0-100.0 s |
| | Braking current value: 0.0% -100.0% |
| Control in JOG mode | JOG frequency range: 0.00-50.00 Hz |
| (stepping) | JOG acceleration/ deceleration time 0.0-6500.0 s |
| Implemented more preset | Implemented up to 16 speeds using a simple |
| speeds | PLC function or a combination of X end states. |
| Built-in PID regulator | Facilitates a process-controlled closed-loop control system. |
| Automatic AVR | It can automatically maintain a constant output voltage |
| voltage regulation | when the supply voltage changes. |
| Overvoltage and overcurrent | Current and voltage are automatically limited during operation to prevent |
| control | frequent tripping due to overvoltage and overcurrent. |
| Tenning I to 111 - 100 - 1 - 1 | It can automatically limit torque and prevent frequent |
| Torque Limiting and Control | overcurrent changes during operation. |
| EMS STOP | "Emergency Stop" system: stops the drive immediately |
| emergency feature | in an emergency, after activating EMS STOP. |
| Fast current limit | Helps prevent common errors due to AC motor overcurrent |
| | AC motor control is performed by high-performance |
| High performance | vector current control technology. |
| | |

| Time management | Time range: 0.0-6500 minutes |
|-------------------------------|--|
| Communication protocol | RS485 MODBUS RTU |
| Boot command channel | Depending on the panel, control terminals, the serial communication |
| | port can be switched in many ways |
| Frequency source | 10 types of frequencies, given by digital analog voltage, |
| | analog current, pulse, serial port, can be |
| | switched in many ways |
| | 10 kinds of frequencies, micro adjustment can |
| Auxiliary frequency source | be easily implemented, frequency synthesizer |
| | 6 digital inputs |
| Input terminals | 2 analog inputs, one of which only supports 0-10V input |
| | and the other supports 0-10V or 4-20mA input. |
| | 1 digital output, |
| Output terminals | 1 relay output, |
| | 1 analog output terminal with 0-20 mA / 0-10 V output |
| PTC | Input for PTC protection of the electric motor |
| LED display | Displays parameters |
| Lock keys and select features | Can block buttons partially or completely and define the range of functions of some buttons to prevent malfunctions |
| Protection mode | Motor short-circuit detection, output phase loss protection, overcurrent protection, overvoltage protection, live protection, overheat protection and overload protection. |
| EMC (compatibility) | IE 61000-4-6; IEC 61000-4-4; IEC 61000-4-11; IEC 61000-4-5 |
| | EN/IEC 61800-3:2017; C1, which is suitable for the 1st environment |
| Standards | EN/IEC 61800-3:2017; C2, which is suitable for the 1st environment |
| | Inside, avoid direct sunlight, salt, dust, corrosive or flammable gas, smoke, |
| Installing in an environment | steam. Resistance to chemical contaminants class 3C3 EN/IEC 60721-3-3 |
| | Dust pollution resistance 3S3 EN/IEC 60721-3-3. |
| Altitude | Under 1000 meters above sea level (reduce the degree of load when used above 1000 meters above sea level.) |
| Ambient temperature | -10 °C ~ 40 °C (reduce power level if ambient temperature is between 40 °C and 50 °C |
| Humidity | Less than 95% relative humidity, no condensation IEC 60068-2-3 |
| Vibration | Less than 5,9 m/s2 (0,6g) IEC 60068-2-6 |
| Storage temperature | - 20 °C to + 60°C |

